

Amendments to the Specification:

Please amend paragraph 24 as follows:

Q1 Figure 9 is an enlarged view of conveyor 112. Conveyor 112 includes a carriage 142 that slides on rails 144, 146, and 148. A bracket 150, secured to carriage 142 by screws 152 or the like, attaches grasper 110 to carriage 142. A fluid, such as air, supplied to conveyor 112 by ~~fluid-flow lines 156 and 158~~ fluid-flow lines 154 and 156, as shown in Figure 8, causes carriage 142 to slide on rails 144, 146, and 148, thereby moving grasper 110 along axis 114. Figure 8 also shows that fluid-flow lines 154 and 156 are connected to an electromechanical valve 158, such as a solenoid valve (e.g., the NVJ5140 available from SMC Corporation, Tokyo, Japan), that is connected to a fluid supply by a fluid-flow line 160. Controller 116 is electrically connected to electromechanical valve 158 by a cable 162. Controller 116 is electrically connected to printer 102 by a cable 164.

Please amend paragraph 22 as follows:

Q2 Grasper 110 also includes an actuator 122 (e.g., ~~Parallel Gripper~~ PARALLEL GRIPPER RP-50P available from Robohand, Inc., Monroe, CT, USA) for moving jaw 118 along an axis 124 that is approximately perpendicular to tear-off edge 108. Therefore, actuator 122 moves jaw 118 approximately perpendicularly to tear-off edge 108. Printer 102 is positioned at an angle 126 relative to axis 114, as shown in Figure 1, where angle 126 ranges from approximately zero to ten degrees. In one embodiment, angle 126 ranges from approximately four to seven degrees. Actuator 122 moves jaw 118 into engagement with paper tape 104 to grasp paper tape 104 between jaws 118 and 120 and out of engagement with paper tape 104 for releasing paper tape 104 from between jaws 118 and 120. In one embodiment, screws 128, or the like, attach jaw 120 approximately perpendicularly to actuator 122 so that jaw 120 cannot move relative to actuator 122, and screws 131, or the like, secure jaw 118 to a slide 130 of actuator 122. Figure 5 shows that slide 130 of actuator 122 is oriented at angle 126 with respect to the conveyor; that is, slide 130 moves along axis 124, which forms angle 126 with axis 114.